

Name: \_\_\_\_\_

Class: \_\_\_\_\_

## Post-Evaluation Survey

**Directions: Please answer all questions as best as you can. Be honest and clear when explaining. This sheet will not be graded.**

What are the two types of turns a robot can do?

What is the difference between the two turns?

What are the advantages of each turn?

Write a sample code in RobotC for each type of turn. Place comments describing important lines of the code.

Name: \_\_\_\_\_

Class: \_\_\_\_\_

What parts of the robot affect how the robot turns?

What parts of the robot affect how we write a program to make the robot turn?

Can we use what we learned today in the real world? How?

What did you like or dislike about this lesson?